

TECHNICAL MANUAL
optibelt DELTA Chain



OPTIBELT

TECHNICAL MANUAL

optibelt DELTA Chain



The **optibelt DELTA Chain** sets new standards in the market for high performance timing belts. Endless **optibelt DELTA Chain** high performance timing belts together with the associated ZRS DC timing belt pulleys enable slip-free synchronous power transmission of up to several hundred kilowatts.

An up to 100% higher power transmission is possible compared to high performance rubber timing belts such as **optibelt OMEGA HP**. The particular focus here is on drives with very high torques. In general, the overall width can be considerably reduced for power drives with small and medium centre distances.

The innovative combination of materials comprising an extremely resistant polyurethane compound, an abrasion-resistant and specially treated polyamide fabric, as well as a carbon fibre cord, provides the **optibelt DELTA Chain** with unmatched strength and resistance to a wide range of chemicals, oils and fluids.

This means that the **optibelt DELTA Chain** is suitable for a wide variety of applications, including uses which were previously reserved for roller chains, for example.

All relevant information as well as the methods to calculate drives with **optibelt DELTA Chain** high performance timing belts are included in this manual. They are supplemented by the Optibelt product ranges and price lists for belts and pulleys, technical data sheets, the optibelt CAP software for drive design, CAD drawings of optibelt ZRS DC toothed pulleys and additional Optibelt documentation, which can be found in their current version on the Optibelt website.

If you have any further questions, please take advantage of the free service provided by our application engineers.

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TABLE OF CONTENTS



Introduction	1
Sales Organisation of the Arntz Optibelt Group	2 - 3
1 PRODUCT DESCRIPTION	
1.1 Structure	6
1.2 Features	7
1.3 Dimensions and Tolerances	8 - 9
2 TIMING BELT PRODUCT RANGE	
2.1 The optibelt DELTA Chain 8MDC	10
2.2 The optibelt DELTA Chain 14MDC	11
3 DRIVE DESIGN	
3.1 Formula Symbols	12
3.2 Pre-Selection of the Profiles	13
3.3 Drive Service Factors	14
3.4 Additional Factors and Minimum Allowances	15
3.5 Formulae and Calculation Example	16 - 17
3.6 Belt Tension Adjustment by Frequency Measurement	18

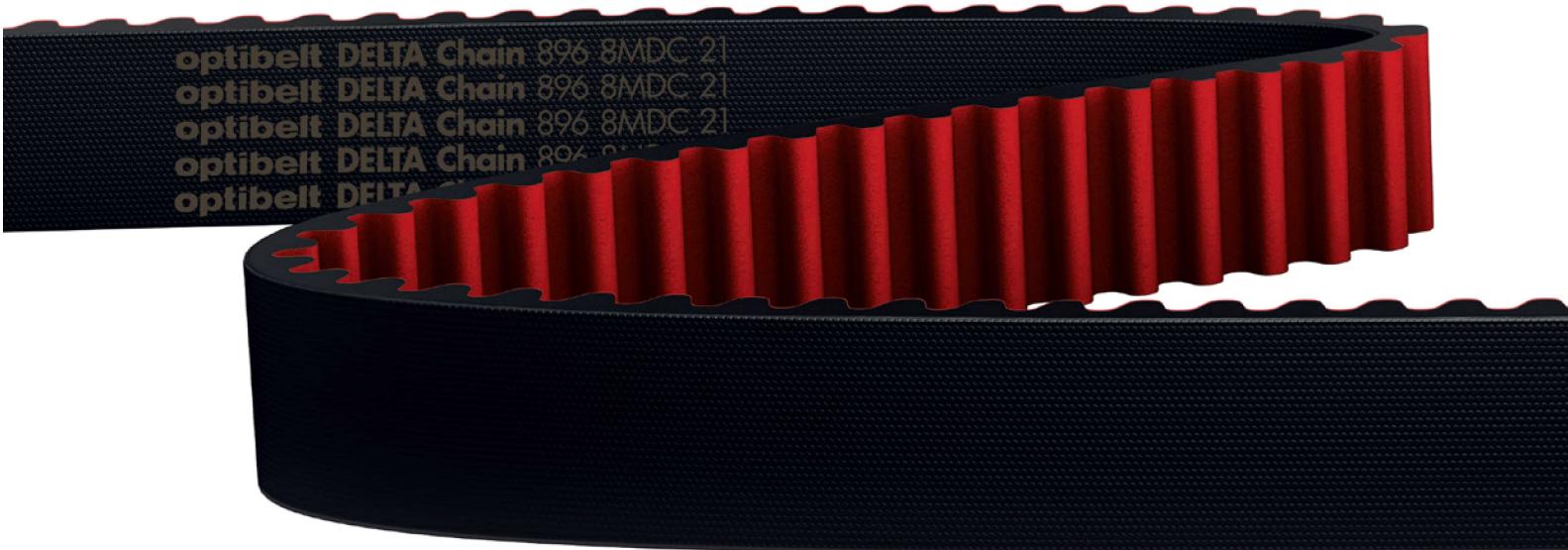


TABLE OF CONTENTS



4 POWER RATINGS

4.1 The optibelt DELTA Chain 8MDC	19
4.2 The optibelt DELTA Chain 14MDC	20

5 DESIGN HINTS

5.1 Timing Belt Pulleys / Tension Idlers	21
5.2 Installation and Maintenance	22
5.3 Problems – Causes – Remedies	23

6 TOOTHED PULLEYS

6.1 Minimum Pulley Diameter and Designs	24
6.2 Dimensions and Tolerances	25 - 26
6.3 Taper Bush Range	27
6.4 Toothed Pulley Range	28 - 33

7 GENERAL INFORMATION

7.1 Overview of Standards	34
7.2 Data Sheet for Calculation	35



1 PRODUCT DESCRIPTION

1.1 STRUCTURE



TEETH

The teeth and also the top layer are made of high-strength cast polyurethane or thermoset and an extremely wear-resistant fabric. Both features give the teeth outstanding shear strength.

TOOTH-SIDE FABRIC

The shear strength of the teeth is enhanced by a strong, coated and well-bonded fabric. Friction between the belt and the pulley is also reduced. This reduces the degree to which the friction partners heat up and minimises the running noise.

TOOTH PROFILE

The curved tooth profile of the **optibelt DELTA Chain** timing belt ensures that it perfectly meshes and engages with the precisely fitting grooves on the matching **optibelt ZRS DC** pulleys. This tooth profile is not compatible with Omega or HTD, RPP and STD profiles. Consequently, the use of **optibelt DELTA Chain** timing belts is only recommended for **optibelt ZRS DC** pulleys or CTD or PC pulleys with the same profile. These and all other significant curved profiles, particularly including those of the pulleys referred to above, are standardised in ISO 13050.

TENSION CORD

In contrast to rubber and polyurethane timing belts e.g. the **optibelt ALPHA** product groups, a tension cord made of carbon fibres is used. This stands out particularly with its ability to transmit extremely high forces. Carbon cord achieves unmatched length stability and outstanding breakage resistance in comparison to all other tension cords such as those made of glass, steel or aramid. **optibelt DELTA Chain** timing belts must not be bent otherwise the carbon tension cord will be damaged.

TOP SURFACE

The smooth top surface of the belt consists of an abrasion-resistant, thin, and thus bendable polyurethane compound. Due to the smooth top surface as opposed to a grooved structure, a back bend idler can be used without any significant increase in the noise level.



1 PRODUCT DESCRIPTION

1.2 FEATURES



POWER TRANSMISSION

An up to 100% higher power transmission is possible compared to high performance rubber timing belts such as the **optibelt OMEGA HP**. The particular focus here is on drives with very high torques. In general, the overall width can be considerably reduced for power drives with small and medium centre distances.

RESISTANCE TO CHEMICALS

Due to the materials used, especially the cast polyurethane used in this case, the **optibelt DELTA Chain** exhibits good to very good resistance to oils, greases and a large number of aggressive chemicals when compared to rubber. Verification of the selected drive in tests is generally recommended. Simple swelling tests should be performed in advance.

TEMPERATURE RESISTANCE

The timing belt withstands temperatures of approx. -30°C to $+80^{\circ}\text{C}$. Temperatures exceeding this level may result in premature failure of the belt.

EFFICIENCY

Timing belt drives operate synchronously with positive engagement power transmission, i.e. without speed loss, in contrast to drives with frictional power transmission. Despite the high-strength polyurethane, the belt is still flexible in the bending direction, and the specially developed tooth fabric provides almost frictionless engagement with the teeth, resulting in up to 98% efficiency.

NOISE EMISSIONS

The optimised tooth shape and the coated, tooth-facing fabric minimise friction and the noise that occurs when the tooth engages with the pulley. Moreover, by reducing the belt width by up to 50% compared to high performance rubber timing belts, the noise component caused by air displacement is also considerably reduced. This means overall that the relatively hard **optibelt DELTA Chain** is able to match, or even improve on, the noise level of rubber timing belts, especially compared to much wider standard rubber or polyurethane timing belts.

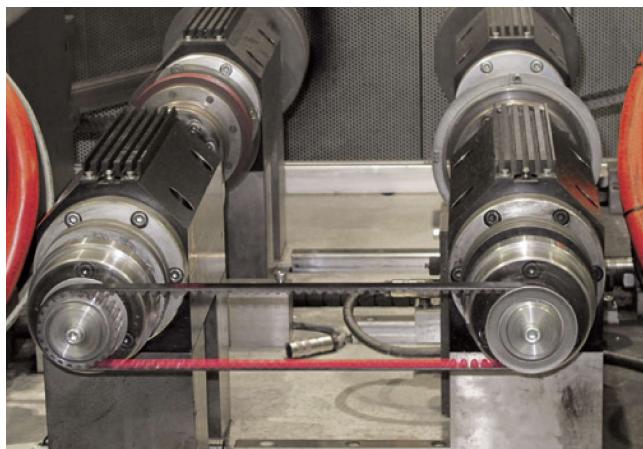


Figure 1.2.1: Test bench

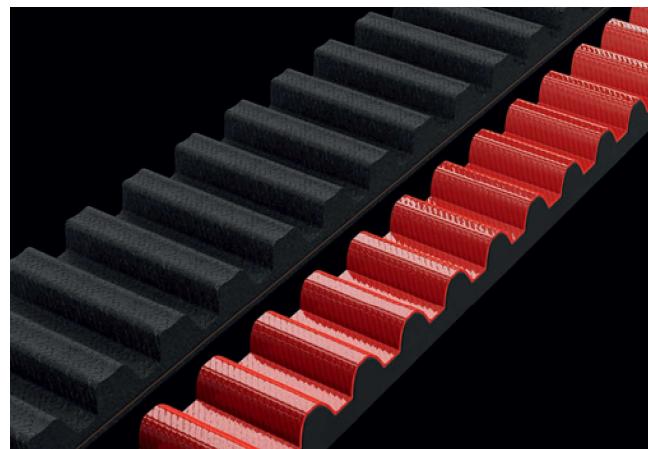


Figure 1.2.2: Reduced width

1 PRODUCT DESCRIPTION

1.3 DIMENSIONS AND TOLERANCES



Table 1.3.1: Nominal dimensions and weights per metre

Profile	Tooth pitch	Overall height	Tooth height	Metre weight per mm width
	t [mm]	h [mm]	h _t [mm]	[kg/(m * mm)]
8MDC	8.0	5.9	3.43	0.0048
14MDC	14.0	9.8	6.0	0.0083

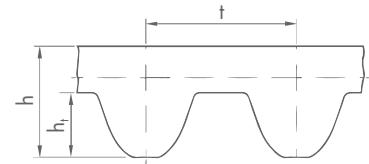


Figure 1.3.1: Profile DC

LENGTH TOLERANCES

The length tolerances indicated in Table 1.3.2 refer to the centre distance. The measuring arrangement is shown in Figure 1.3.2.

Table 1.3.2: Length Tolerances

Timing belt length L _w [mm]	Length tolerance a _{Ltol} [mm]
< 760	± 0.30
> 786	< 1016
> 1022	< 1272
> 1274	< 1520
> 1526	< 1778
> 1784	< 2032
> 2040	< 2282
> 2288	< 2536
> 2544	< 2792
> 2800	< 3048
> 3052	< 3304
> 3312	< 3566*

*For longer lengths, 0.03 mm have to be added for each increment of 250 mm.

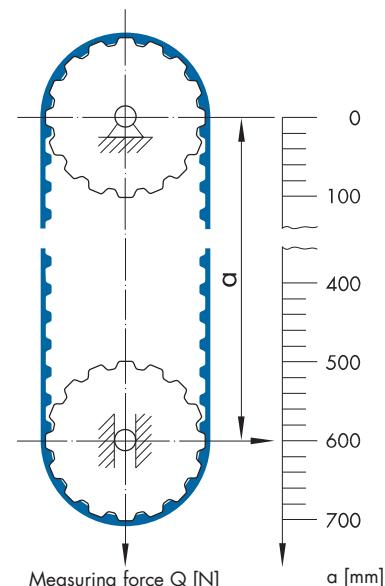


Figure 1.3.2: Arrangement to measure the belt length

Table 1.3.3: Measuring forces to determine the belt length

Profile	Width [mm]								
	12	20	21	36	37	62	68	90	125
Measuring force [N]									
8MDC	267		467	756		1223			
14MDC		1179			2046		3447	4315	5627

1 PRODUCT DESCRIPTION

1.3 DIMENSIONS AND TOLERANCES



Table 1.3.4: Width tolerance

Profile	Width [mm]	Permissible tolerance of belt width [mm]		
		Pitch length L_w $\leq 840 \text{ mm}$	Pitch length L_w $> 840 \text{ mm} \leq 1680 \text{ mm}$	Pitch length L_w $> 1680 \text{ mm}$
8MDC	< 12	± 0.4	$+0.4/-0.8$	± 0.8
	$\geq 12 < 21$	± 0.8	$+0.8/-1.2$	$+0.8/-1.2$
	$\geq 21 < 36$	± 0.8	$+0.8/-1.2$	$+0.8/-1.2$
	$\geq 36 < 62$	± 0.8	$+0.8/-1.2$	$+0.8/-1.2$
	≥ 62	± 1.2	$+1.2/-1.6$	± 1.6
14MDC	< 20	± 0.8	± 0.8	$+0.8/-1.2$
	$\geq 20 < 37$	± 0.8	$+0.8/-1.2$	$+0.8/-1.2$
	$\geq 37 < 68$	± 0.8	$+0.8/-1.2$	$+0.8/-1.2$
	$\geq 68 < 90$	$+1.2/-1.6$	± 1.6	$+1.6/-2.0$
	$\geq 90 < 125$	± 1.6	$+1.6/-2.0$	± 2.0
	≥ 125	± 2.4	$+2.4/-2.8$	$+2.4/-3.2$

STANDARDIZATION

optibelt DELTA Chain timing belts and optibelt ZRS DC pulleys are standardized in ISO 13050.



2 TIMING BELT PRODUCT RANGE

2.1 optibelt DELTA Chain 8MDC



		Profile	8MDC
t	[mm]	8.0	
h	[mm]	5.9	
h_t	[mm]	3.43	

optibelt DELTA Chain 8MDC					
Profile, length	Pitch length L_w [mm]	Number of teeth	Profile, length	Pitch length L_w [mm]	Number of teeth
8MDC 640	640,00	80	8MDC 3280	3280,00	410
8MDC 720	720,00	90	8MDC 3600	3600,00	450
8MDC 800	800,00	100	8MDC 4000	4000,00	500
8MDC 896	896,00	112	8MDC 4400	4400,00	550
8MDC 960	960,00	120	8MDC 4480	4480,00	560
8MDC 1000	1000,00	125			
8MDC 1040	1040,00	130			
8MDC 1120	1120,00	140			
8MDC 1200	1200,00	150			
8MDC 1224	1224,00	153			
8MDC 1280	1280,00	160			
8MDC 1440	1440,00	180			
8MDC 1600	1600,00	200			
8MDC 1760	1760,00	220			
8MDC 1792	1792,00	224			
8MDC 2000	2000,00	250			
8MDC 2200	2200,00	275			
8MDC 2240	2240,00	280			
8MDC 2400	2400,00	300			
8MDC 2520	2520,00	315			
8MDC 2600	2600,00	325			
8MDC 2800	2800,00	350			
8MDC 2840	2840,00	355			
8MDC 3048	3048,00	381			
8MDC 3200	3200,00	400			

Please also refer to the current product range or inquire about other dimensions.

Standard widths: 12 mm, 21 mm, 36 mm, 62 mm
Intermediate widths on request

Example order:

optibelt DELTA Chain 1120 8MDC 21

1120 = pitch length L_w [mm]

8MDC = profile

21 = width [mm]

2 TIMING BELT PRODUCT RANGE

2.2 optibelt DELTA Chain 14MDC



		Profile	14MDC
t	[mm]	14.0	
h	[mm]	9.8	
h_t	[mm]	6.0	

optibelt DELTA Chain 14MDC					
Profile, length	Pitch length L_w [mm]	Number of teeth	Profile, length	Pitch length L_w [mm]	Number of teeth
14MDC 994	994.00	71	14MDC 3920	3920.00	280
14MDC 1120	1120.00	80	14MDC 4326	4326.00	309
14MDC 1190	1190.00	85	14MDC 4410	4410.00	315
14MDC 1260	1260.00	90			
14MDC 1400	1400.00	100			
14MDC 1568	1568.00	112			
14MDC 1610	1610.00	115			
14MDC 1750	1750.00	125			
14MDC 1778	1778.00	127			
14MDC 1890	1890.00	135			
14MDC 1960	1960.00	140			
14MDC 2100	2100.00	150			
14MDC 2240	2240.00	160			
14MDC 2310	2310.00	165			
14MDC 2380	2380.00	170			
14MDC 2450	2450.00	175			
14MDC 2520	2520.00	180			
14MDC 2590	2590.00	185			
14MDC 2660	2660.00	190			
14MDC 2800	2800.00	200			
14MDC 3136	3136.00	224			
14MDC 3304	3304.00	236			
14MDC 3360	3360.00	240			
14MDC 3500	3500.00	250			
14MDC 3850	3850.00	275			

ALL DIMENSIONS ON REQUEST!

Please also refer to the current product range
or inquire about other dimensions.

Standard widths: 20 mm, 37 mm, 68 mm, 90 mm, 125 mm
Intermediate widths on request

Example order:

optibelt DELTA Chain 1400 14MDC 37

1400 = pitch length L_w [mm]

14MDC = profile

37 = width [mm]

3 DRIVE DESIGN

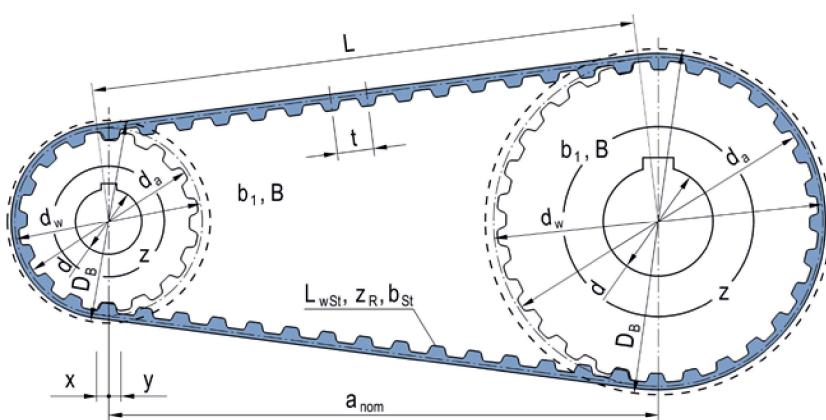
3.1 FORMULA SYMBOLS



Table 3.1.1: Formula symbols

Formula symbols	Explanation	Unit	Formula symbols	Explanation	Unit
a	Drive centre distance	[mm]	n_2	Speed of the driven timing belt pulley	[min ⁻¹]
a_{nom}	Drive centre distance, calculated with a standard belt length	[mm]	P	Power to be transmitted from timing belt drive	[kW]
c_0	Base drive service factor		P_B	Design power	[kW]
c_1	Tooth meshing factor		P_N	Rated power	[kW]
c_2	Total drive service factor		P_U	Power transmitted from a standard belt width $[P_N \cdot c_1 \cdot c_7]$	[kW]
c_3	Speed ratio correction factor		F_a	Minimum static shaft loading	[N]
c_6	Fatigue allowance		$F_{n \text{ perm}}$	Maximum permitted circumferential force	[N]
c_7	Length factor		F_{n3}	Circumferential force to be effectively transmitted	[N]
d_a	Outside diameter of timing belt pulley	[mm]	F_n	Circumferential force to be effectively transmitted incl. actual centrifugal force	[N]
d_w	Pitch diameter of timing belt pulley	[mm]	t	Tooth pitch	[mm]
d_{wg}	Pitch diameter of large timing belt pulley	[mm]	v	Belt speed (velocity)	[m/s]
d_{wk}	Pitch diameter of small timing belt pulley	[mm]	x	Minimum allowance of the drive centre distance a_{nom} for installation of the timing belt	[mm]
d_{w1}	Pitch diameter of driving pulley	[mm]	z_e	Number of meshed teeth of the small driving pulley	
d_{w2}	Pitch diameter of driven pulley	[mm]	z_g	Number of teeth of the large driving pulley	
E_a	Belt deflection for a given span length	[mm]	z_k	Number of teeth of the small driving pulley	
F	Test force	[N]	z_R	Number of teeth of the timing belt	
f	Frequency	[Hz]	z_1	Number of teeth of the driving pulley	
i	Speed ratio		z_2	Number of teeth of the driven pulley	
L	Span length	[mm]			
L_{wSt}	Standard pitch length of the timing belt	[mm]			
L_{wth}	Calculated pitch length of the timing belt	[mm]			
n_1	Speed of the driving pulley	[min ⁻¹]			

Figure 3.1.1: Example of a drive geometry: Belts and pulleys



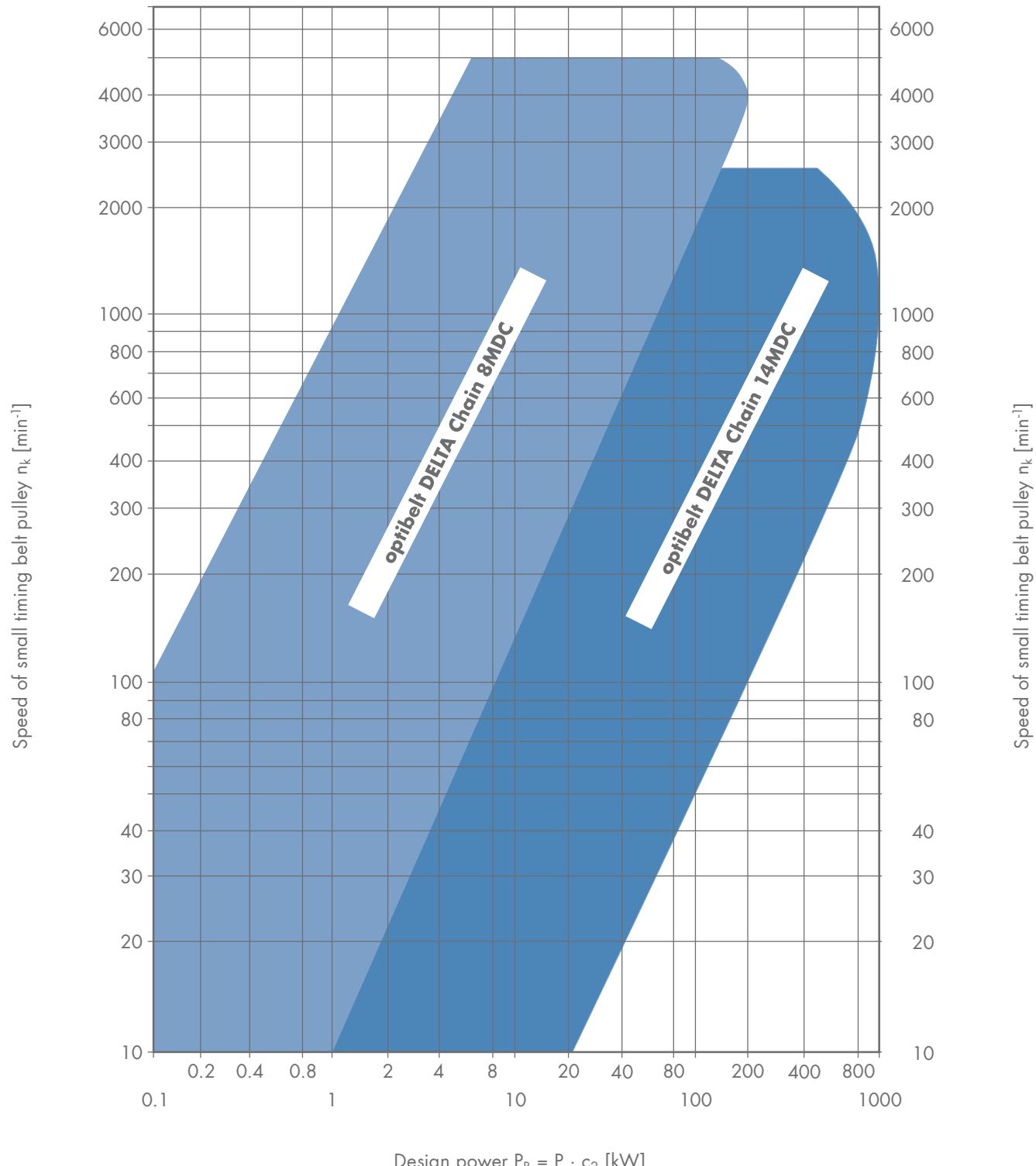
3 DRIVE DESIGN

3.2 PRE-SELECTION OF THE PROFILES



Graph 3.2.1: Pre-selection of profiles 8MDC and 14MDC

See also optibelt CAP drive calculation,
software at www.optibelt.com



3 DRIVE DESIGN

3.3 DRIVE SERVICE FACTORS



TOTAL DRIVE SERVICE FACTOR c_2

The total drive service factor c_2 is composed of the base drive service factor c_0 and two further allowances c_3 and c_6 .

$$c_2 = c_0 + c_3 + c_6 \quad [-]$$

$$c_2 \geq \frac{M_A}{M_N}, \quad c_2 \geq \frac{M_{Br}}{M_N} \quad [-] \quad \text{at drive} \quad \text{with } M_A \text{ [Nm]}, M_N \text{ [Nm]} \text{ and } M_{Br} \text{ [Nm]}$$

$$c_2 \geq \frac{M_{Br}}{M_N \cdot i} \quad [-] \quad \text{at driven side} \quad \text{with } M_N \text{ [Nm]}, M_{Br} \text{ [Nm]} \text{ and } i \text{ [-]}$$

The total drive service factor c_2 should also consider a high starting load M_A and a high braking load M_{Br} at the drive or a high braking load at the driven side in proportion to the rated load M_N of the driving machine.

With frequent switching operations and high starting or braking loads, which thus become the main load, while the power transmission itself recedes into the background, an additional safety allowance must be added to the maximum determined quotient.

Table 3.3.1: Base drive service factor c_0

c_0 Type of base load and examples of a driven machine	Load type and examples of driving machines					
	Uniform run Electric motor Fast-moving turbine Piston machine with high number of cylinders	Irregular operation Hydraulic motor Slow-moving turbine Piston machine with low number of cylinders	Base drive service factor c_0 for daily operating time			
			up to 16 h	above 16 h	up to 16 h	above 16 h
Light drives, joint-free and uniform running Measuring instruments Film cameras Office equipment Belt conveyors (light goods)	1.3	1.4	1.4	1.5		
Medium drives, temporary operation with small to medium impact loading Mixing machines Food processors Printing machines Textile machines Packaging machines Belt conveyors (heavy goods)	1.6	1.7	1.8	1.9		
Heavy drives, operation with medium to strong temporary impact load Machine tools Wood processing machines Eccentric drives Conveying systems (heavy goods)	1.8	1.9	2.0	2.1		
Very heavy drives, operation with strong permanent impact load Mills Calenders Extruders Piston pumps and compressors Lifting gear	2.0	2.1	2.2	2.3		

3 DRIVE DESIGN

3.4 ADDITIONAL FACTORS AND MINIMUM ALLOWANCES



BASE DRIVE SERVICE FACTOR c_0

The base drive service factor c_0 takes into account the daily operating time and the type of driver and driven units.

As it is not possible to summarise any thinkable combination of driver, driven unit and operating conditions in one table, the base drive service factors are to be considered as guide values. The assignment of the driven unit depends on the type of load that is present in each case.

For slowly operating drives with a speed of $\leq 100 \text{ min}^{-1}$, a base drive service factor of at least 2 is recommended.

SPEED RATIO CORRECTION FACTOR c_3

For the speed step-up ratios, the value that corresponds to the speed ratio is added to the base drive service factor c_0 .

Table 3.4.1: Speed ratio correction factor

Speed ratio i	Speed ratio correction factor c_3
≥ 0.80	0.0
$< 0.80 \geq 0.57$	0.1
$< 0.57 \geq 0.40$	0.2
$< 0.40 \geq 0.28$	0.3
< 0.28	0.4

Table 3.4.4: Tooth meshing factor c_1

Number of meshed teeth	Tooth meshing factor c_1
≥ 6	1.0
5	0.8
4	0.6
3	0.4
2	0.2

Minimum allowance x for tensioning timing belts

$$x = 0.004 \cdot a_{\text{hom}}$$

Table 3.4.2: Fatigue allowance c_6

Drive conditions	Fatigue allowance c_6
Use of tension or idler pulleys	0.2
Operating time 16–24 h	0.2
Only rare or occasional operation	– 0.2

Table 3.4.5: Minimum allowance y for installation of timing belt pulleys without flange

Drive centre distances [mm]	Minimum allowance y [mm]
≤ 1000	1.8
$> 1000 \leq 1780$	2.8
$> 1780 \leq 2540$	3.3
$> 2540 \leq 3300$	4.1
$> 3300 \leq 4600$	5.3

Table 3.4.3: Length factor c_7

Profile 8MDC		Profile 14MDC	
Pitch length [mm]	c_7	Pitch length [mm]	c_7
≤ 600	0.8	≤ 1190	0.80
$> 600 \leq 880$	0.9	$> 1190 \leq 1610$	0.90
$> 880 \leq 1200$	1.0	$> 1610 \leq 1890$	0.95
$> 1200 \leq 1760$	1.1	$> 1890 \leq 2450$	1.00
$> 1760 \leq 2240$	1.2	$> 2450 \leq 3150$	1.05
$> 2240 \leq 2840$	1.3	$> 3150 \leq 3500$	1.10
$> 2840 \leq 3600$	1.4	> 3500	1.20
> 3600	1.5		

Table 3.4.6: Minimum allowance y for installation of timing belt pulleys with flanges

Profile	Flange on one timing belt pulley [mm]	Flange on both timing belt pulleys [mm]
8MDC	22	33
14MDC	36	58

3 DRIVE DESIGN

3.5 FORMULAE AND CALCULATION EXAMPLE



PRIME MOVER

Electric motor 50 Hz
star-delta connection
 $P = 11 \text{ kW}$
 $n_1 = 1450 \text{ min}^{-1}$

DRIVE CONDITIONS

Operational hours per day: 12 hours
Number of starts: Twice per day
Environmental influences: Ambient temperature,
no influence of oil, water and dust
Drive centre distance: 400 mm to 450 mm
Maximum pulley diameter: 200 mm

DRIVEN MACHINE

Paper machine
 $n_2 = 920 \text{ min}^{-1} \pm 2\%$
Type of load: Constant

FORMULAS

TOTAL DRIVE SERVICE FACTOR

$$c_2 = c_0 + c_3 + c_6$$

c_0 from Table 3.3.1
 c_3 from Table 3.4.1
 c_6 from Table 3.4.2

CALCULATION EXAMPLE

$$c_2 = 1.6 + 0 + 0 = 1.6$$

$c_0 = 1.6$
 $c_3 = 0$
 $c_6 = 0$

DESIGN POWER

$$P_B = P \cdot c_2$$

$$P_B = 11 \cdot 1.6 = 17.6 \text{ kW}$$

TIMING BELT PROFILE

from Graph 3.2.1

optibelt DELTA Chain

Profile 8MDC

RECALCULATION OF SPEED

$$i = \frac{n_1}{n_2} = \frac{z_2}{z_1} = \frac{d_{w2}}{d_{w1}}$$

$$i = \frac{1450}{920} = 1.576$$

NUMBER OF TEETH ON THE TIMING BELT PULLEYS

z_1, d_{w1} Standard timing belt pulleys, see 6.4

$$z_2 = z_1 \cdot i$$

Please observe minimum diameter!

Minimum number of teeth, see Table 6.1.1

$$z_1 = 36 \quad d_{w1} = 91.67 \text{ mm}$$

$$z_2 = 36 \cdot 1.56 = 56.16$$

$$z_2 = 56 \quad d_{w2} = 142.60 \text{ mm}$$

Requirement $z \geq 22$ minimum number of teeth for profile 8MDC met

RECALCULATION OF SPEED

$$i = \frac{z_2}{z_1}$$

$$n_2 = \frac{n_1}{i}$$

$$i = \frac{56}{36} = 1.556$$

$$n_2 = \frac{1450}{1.556} = 932 \text{ min}^{-1}$$

Required:

$$920 \text{ min}^{-1} \pm 2\% \text{ met}$$

RECOMMENDED DRIVE CENTRE DISTANCE

Recommendation

$$a > 0.5 (d_{w1} + d_{w2}) + 15 \text{ mm}$$

$$a < 2.0 (d_{w1} + d_{w2})$$

$$a > 0.5 (91.67 + 142.60) + 15 \text{ mm} = 132.14 \text{ mm}$$

$$a < 2.0 (91.67 + 142.60) = 468.54 \text{ mm}$$

$$a = 425 \text{ mm} \text{ selected provisionally}$$

See also optibelt CAP drive calculation, software at www.optibelt.com

3 DRIVE DESIGN

3.5 FORMULAE AND CALCULATION EXAMPLE



FORMULAS

PITCH LENGTH

$$L_{wth} \approx 2a + \frac{\pi}{2} (d_{wg} + d_{wk}) + \frac{(d_{wg} - d_{wk})^2}{4a}$$

L_{wSt} see timing belt range in Chapter 2

CALCULATION EXAMPLE

$$L_{wth} \approx 2 \cdot 425 + \frac{\pi}{2} (142.60 + 91.67) + \frac{(142.60 - 91.67)^2}{8}$$

$L_{wth} \approx 1219.33 \text{ mm}$ (selected from Subchapter 2.1)

$L_{wSt} = 1200 \text{ mm}$

NOMINAL DRIVE CENTRE DISTANCE

$$a_{nom} = K + \sqrt{K^2 - \frac{(d_{wg} - d_{wk})^2}{8}}$$

$$K = \frac{L_{wSt}}{4} - \frac{\pi}{8} (d_{wg} + d_{wk})$$

$$a_{nom} = 208 + \sqrt{208^2 - \frac{(142.60 - 91.67)^2}{8}}$$

$a_{nom} = 415.22 \text{ mm}$

$$K = \frac{1200}{4} - \frac{\pi}{8} (142.60 + 91.67) = 208 \text{ mm}$$

MINIMUM ALLOWANCE FOR TENSIONING

$$x = 0.004 \cdot a_{nom}$$

$x \geq 1.66 \text{ mm}$

MINIMUM ALLOWANCE FOR INSTALLATION

$y = \text{from Table 3.4.6}$

$y = 33 \text{ mm}$ Flange on both timing belt pulleys

NUMBER OF MESHED TEETH ON THE SMALL PULLEY

$$z_e = \frac{z_k}{6} \left(3 - \frac{d_{wg} - d_{wk}}{a_{nom}} \right) \quad \text{Round down value}$$

$$z_e = \frac{36}{6} \left(3 - \frac{142.60 - 91.67}{415} \right) = 17.26$$

$z_e = 17$

BELT LENGTH CORRECTION FACTOR

c_7 from Table 3.4.3

$c_7 = 1.0$

TOOTH MESHING FACTOR

c_1 from Table 3.4.4

$c_1 = 1.0$

BELT WIDTH OVER RATED POWER

Required: $P_{\bar{U}} \geq P_B$

$P_{\bar{U}}$ = transferable rated power of a standard belt width

$P_{\bar{U}} = P_N \cdot c_1 \cdot c_7$

P_N (profile, b) = $P_N \cdot$ width factor (see Chapter 4)

$21.60 \text{ kW} > 17.6 \text{ kW}$

Requirement met

$$P_{\bar{U}} = 21.60 \cdot 1.0 \cdot 1.0 = 21.60 \text{ kW}$$

$$P_N \text{ (8MDC, } b = 21 \text{ mm)} = 12.34 \cdot 1.75 = 21.60 \text{ kW}$$

Result:

1 pc. optibelt DELTA Chain timing belt

1200 8MDC 21

1 pc. optibelt ZRS DC timing belt pulley

36 8MDC 21

1 pc. optibelt ZRS DC timing belt pulley

56 8MDC 21

3 DRIVE DESIGN

3.6 BELT TENSION ADJUSTMENT BY FREQUENCY MEASUREMENT



TENSION FOR optibelt DELTA Chain TIMING BELT

The correct level of belt tension is of crucial importance for trouble-free transmission of power, and for achieving an acceptable belt service life. Often, tension which is either too high or too low results in early timing belt failure. A belt which is over-tensioned sometimes causes bearing failure in the driver or driven unit.

Adjustment of the specified static span force, e.g. using the thumbprint method, is not a suitable means of tensioning drives correctly in order to fully exploit them economically. Instead of this, adjustment of the static span force through frequency measurement, e.g. using instruments from the **optibelt TT** series, is recommended. The default value for the frequency measurement can be determined using the following formulas.

FORMULA SYMBOLS

β [°] Arc of contact

f [Hz] Frequency

m_k [kg/m] Weight per metre

L [mm] Span length

n_k [1/min] Speed of small pulley

P_N [kW] Rated power

F_a [N] Static drive centre force

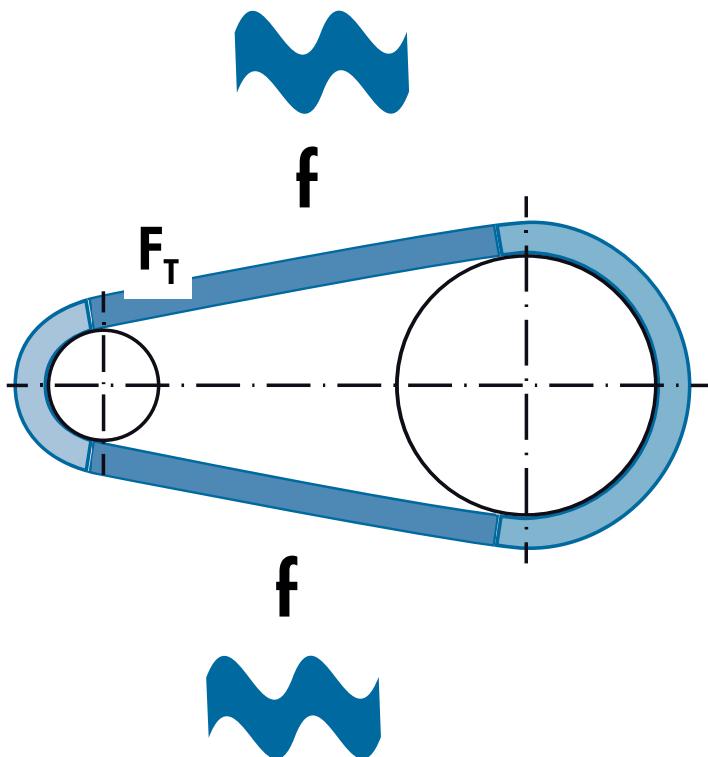
F_u [N] Circumferential force

t [mm] Pitch

F_T [N] Static span force

v [m/s] Circumferential speed

z_k Number of teeth of small pulley



DRIVE CENTRE FORCE, STATIC

$$F_a = 1.4 \cdot \frac{60 \cdot 10^6 \cdot P_N \cdot \sin \frac{\beta}{2}}{t \cdot z_k \cdot n_k}$$

SPAN FORCE, STATIC

$$F_T = \frac{F_a}{2 \cdot \sin \frac{\beta}{2}}$$

CIRCUMFERENTIAL FORCE

$$F_u = \frac{P_N \cdot 1000}{V}$$

FREQUENCY

$$f = \sqrt{\frac{F_T \cdot 10^6}{4 \cdot m_k \cdot L^2}}$$

5 DESIGN HINTS

5.1 TIMING BELT PULLEYS / TENSION IDLERS



FLANGES

To guide Optibelt timing belts, timing belt pulleys should be equipped with flanges on one or both sides.

For drive centre distances $a > 8 d_w$, the timing belt pulleys are to be equipped with flanges on both sides.

We recommend the use of standard timing belt pulleys. If this is not possible for design reasons, corresponding special timing belt pulley designs can be used.



Small pulley with flanges on both sides



Flanges on alternate side



Both pulleys with flanges on both sides

MAXIMUM TIMING BELT WIDTH

The maximum timing belt width should not be larger than the diameter of the smallest timing belt pulley present in the drive.

TENSION IDLERS

Idlers are toothed or flat faced pulleys that do not transmit power within a drive system. Because they create additional bending stresses within the belt, they should be used according to the following guidelines:

- Diameter of the idlers \geq the smallest permitted pulley according to the profile
- Width of the idlers \geq the timing belt pulleys present in the drive
- Always arrange idlers in the empty span
- Inside idlers: ≤ 40 teeth always use timing belt pulley, > 40 teeth flat faced pulley possible
- As outside idlers, flat faced pulleys are to be used in general, as they run on the top surface of the belt
- Flat faced pulleys must not be of spherical shape
- The idlers must be attached in such a way that as many teeth as possible are meshed
- The arc of contact at the idler must be kept as low as possible
- Minimum span width $\geq 2 \cdot$ belt width

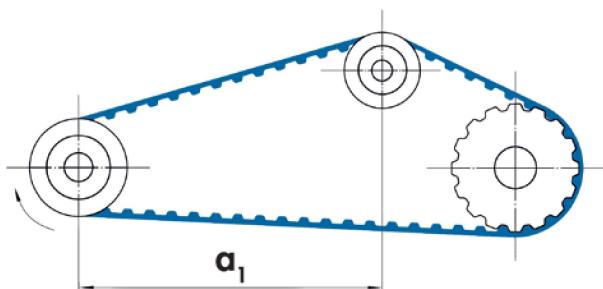


Figure 5.1.1: Arrangement of the inside tension idler

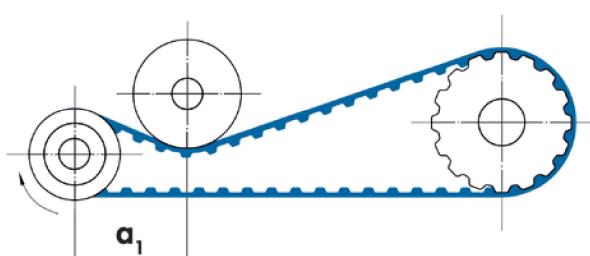


Figure 5.1.2: Arrangement of the outside tension idler

5 DESIGN HINTS

5.2 INSTALLATION AND MAINTENANCE



SAFETY INFORMATION

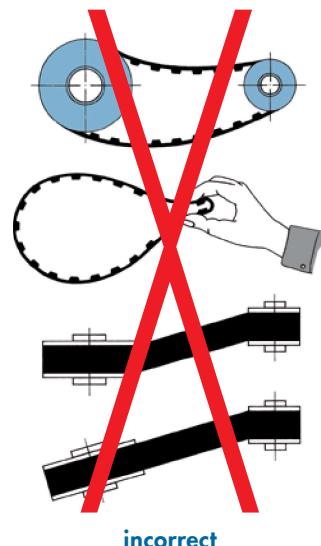
Geometrically correct designing and power rating of drives with Optibelt timing belts ensures high operating reliability and an optimum lifetime. Practice has shown that premature failure can very often be traced to faulty installation or maintenance.

To prevent this, we recommend that you observe the following instructions:



• TIMING BELT PULLEYS

The teeth must be manufactured according to standard and also be clean.

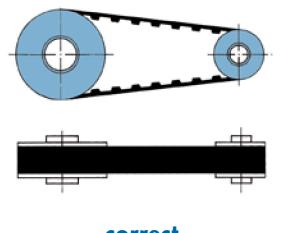


• ALIGNMENT

Shafts and pulleys should be correctly aligned prior to belt installation.

Maximum deviations of shaft parallelism:

Belt width	Angular misalignment
≤ 25	$\pm 1^\circ$
$> 25 \leq 50$	$\pm 0.5^\circ$
$> 50 \leq 100$	$\pm 0.25^\circ$
$> 100 \leq$	$\pm 0.15^\circ$



• TIMING BELT SETS

Timing belts which run in pairs or groups on one drive must always be ordered as a set. This guarantees that all belts originate from the same batch and are identical in length.

• INSTALLATION

Prior to installation, the drive centre distance must be reduced to enable the timing belt to be fitted easily.

If this is not possible, the timing belt must be installed together with one or both timing belt pulleys. Forcing belts over the pulley flanges must be avoided as the damage this causes to the high-quality low-stretch tension members is often not visible. If taper bushes are used, the studs used should be checked after an operating time of 0.5 to 1 hour with the aid of a torque spanner.

• TENSION

The tension must correspond to the guidelines in Chapter 3.6. Further inspections after installation are not necessary.

• TENSION IDLERS

Tension idlers are to be avoided. If this is not possible, refer to the recommendations in Subchapter 5.1 of this manual.

• MAINTENANCE

Optibelt timing belts are maintenance-free if used under normal ambient conditions. If there is clearly visible wear on belts and/or pulleys, they should be replaced; see instructions in Subchapters 5.3 and 6.2.

5 DESIGN HINTS

5.3 PROBLEMS – CAUSES – REMEDIES



Problem	Cause	Remedy
Heavy wear on the loaded tooth faces of the belt	Belt undertensioned Incorrect pulley profile Pitch error	Correct the tension Check profile and replace, if necessary Use wider belts with higher transmission power
Excessive wear at base of tooth on belt	Excessive belt tension Drive under-dimensioned Faulty timing belt pulleys	Reduce tension Enlarge timing belts or pulleys Replace timing belt pulleys
Unusual wear on belt edges	Improper drive centre parallelism Faulty flanges Change of drive centre distance	Re-align the shafts Replace the flanges Reinforce bearing or housing
Belt teeth shearing off	Overloading Too few teeth in mesh Ambient temperature above 80°C	Increase diameter of small pulley or select wider belt Use wider belts or larger pulleys For ambient temperature above 80°C re-design with optibelt OMEGA HP EPDM -40°C / +140°C
Excessive lateral belt movement	Improper drive centre parallelism Timing belt pulleys are not aligned Impact loading with too high belt tension	Re-align the shafts Align the pulleys Reduce belt tension
Detachment of flanges	Timing belt pulleys not in line Very high lateral pressure of the timing belt Incorrect flange installation	Re-align the timing belt pulleys Re-align the shafts Install flanges correctly
Apparent belt stretch	Incorrect storage	Correct the belt tension, reinforce and secure bearing support
Excessive operating noise	Incorrect shaft alignment Belt tension too high Pulley diameter too small Overloading of timing belt Belt width too wide with high speed	Re-align the shafts Reduce the tension Increase pulley diameter Increase belt width or tooth meshing Reduce belt width by selecting larger belt types
Abnormal wear of timing belt pulleys	Unsuitable material Incorrect tooth meshing Insufficient surface hardness	Use stronger material Replace timing belt pulleys Use harder material or harden surface
Cracks on belt top surface	Ambient temperatures below -30°C	Re-design with optibelt OMEGA HP EPDM -40°C / +140°C Provide heating for drive unit
Softening of the belt top surface	Influence of incompatible media	Shield from the media or use a suitable belt quality

6 TOOTHED PULLEYS

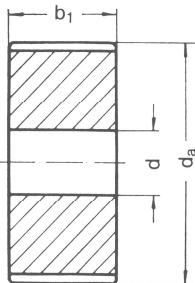
6.1 MINIMUM PULLEY DIAMETER AND DESIGNS



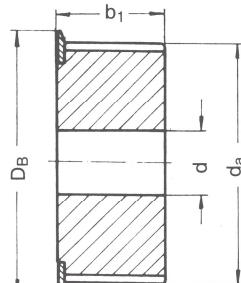
Do not use less than the recommended minimum number of teeth for pulleys, see Table 6.1.1. A pulley diameter that is smaller than the minimum pulley diameter may lead to a reduced operational reliability and an unsatisfactory operating time.

Table 6.1.1: Minimum number of teeth and minimum diameter

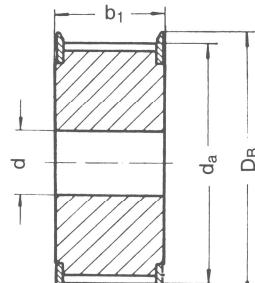
Profile	Minimum number of teeth	Minimum diameter [mm]
8MDC	22	56.02
14MDC	28	124.78



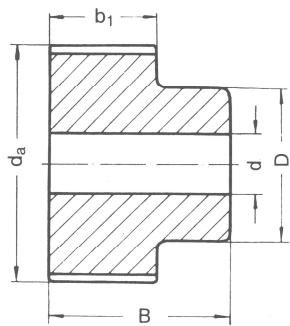
OB type



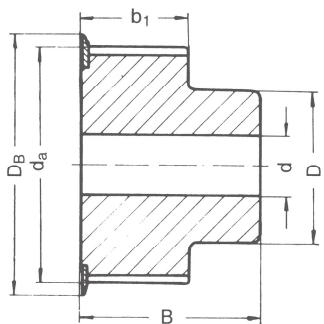
EB type



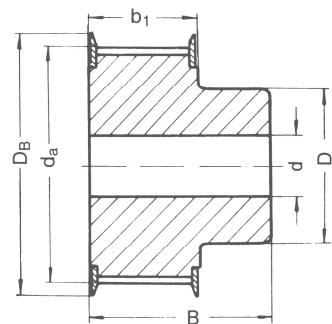
ZB type



OBN type



EBN type



ZBN type

MATERIALS

Steel, grey cast iron, aluminium;
further materials on request
For speeds > 30 m/s, do not use cast pulleys
beyond this speed!

BORES

All timing belt pulleys are pilot bored.
On request they can be finish bored according to DIN H7.

EXPLANATION OF THE ABBREVIATIONS

- OB without flanges
- EB one flange
- ZB two flanges
- OBN without flanges, with hub
- EBN one flange, with hub
- ZBN two flanges, with hub

6 TOOTHED PULLEYS

6.2 DIMENSIONS AND TOLERANCES



PERMISSIBLE DEVIATION OF THE TOOTH SPACINGS

The permissible deviations in the tooth spacing between two consecutive teeth, and of the sum of deviations within a 90° arc, are indicated in the following table. These tolerances represent the spacing between the corresponding points on the right and left surfaces of consecutive teeth.

Table 6.2.1: Permissible deviation of the tooth spacings

Outside diameter d_o [mm]	Permissible deviation of the tooth spacing [mm]	
	between two consecutive teeth	Sum within a 90° arc
> 50 ≤ 100	0.03	0.10
> 100 ≤ 175	0.03	0.13
> 175 ≤ 300	0.03	0.15
> 300 ≤ 500	0.03	0.18
> 500	0.03	0.20

Table 6.2.2: Permissible deviation of the outside diameter

Outside diameter d_o [mm]	Permissible deviation [mm]
> 50 ≤ 100	+ 0.10 0
> 100 ≤ 175	+ 0.13 0
> 175 ≤ 300	+ 0.15 0
> 300 ≤ 500	+ 0.18 0
> 500	+ 0.20 0

The **optibelt DELTA Chain** high performance timing belts feature outstanding longitudinal stiffness due to the tension cord made of carbon fibres. Especially for drives with short drive centre distances or span lengths, and/or large belt widths, a reduction may be required in the permissible deviation specified for the outside diameter and the running tolerances. Tension force fluctuations and additional loads on bearings, shafts and the belt can be minimised in this way.

Table 6.2.3: Pulley width

Profile	Pulley width designation	For belt width [mm]	Smallest pulley width with flanges b_f^* [mm]	without flanges b [mm]
8MDC	12	12	14	18
	21	21	23	27
	36	36	38	42
	62	62	65	69
14MDC	20	20	23	27
	37	37	40	46
	68	68	71	77
	90	90	95	101
	125	125	130	136

* b_f = pulley width between the flanges

NOTE

The minimum width b for pulleys without flanges can be reduced, if the straight running of the drive can be adjusted. However, this must not be below the minimum width indicated for pulleys with flanges b_f .

Table 6.2.4: Side wobble tolerance

Outside diameter d_o [mm]	Maximum total variation [mm]
≤ 100	0.10
> 100 ≤ 250	0.01 mm per 10 mm outside diameter
> 250	0.25 mm + 0.0005 mm per mm outside diameter above 250.00 mm

Table 6.2.5: Run-out tolerance

Outside diameter d_o [mm]	Maximum total variation [mm]
≤ 200	0.10
> 200	0.0005 mm per 10 mm outside diameter, however not larger than the outside diameter tolerance

6 TOOTHED PULLEYS

6.2 DIMENSIONS AND TOLERANCES



Table 6.2.6: Static balancing

Steel pulleys machined on all sides must not be balanced if the circumferential speed is less than 30 m/s. Grey cast iron pulleys for medium speeds should be statically balanced as follows:

Profile	Number of teeth	Static balancing [N]
8MDC	≤ 130	0.08
	> 130	0.16
14MDC	≤ 72	0.08
	> 72	0.16

Timing belt pulleys that are used for a circumferential speed of more than 30 m/s must be dynamically balanced up to $1.8 \cdot 10^{-5}$ Nm.

PARALLELISM

The teeth should be parallel to the centre of the bore with a maximum deviation of 0.001 mm per millimetre of width.

CONICITY

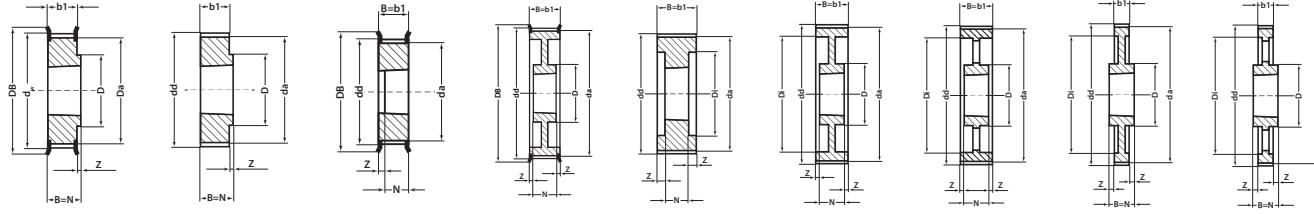
The conicity must not be higher than 0.001 mm per millimetre of head width and must not exceed the permissible outside diameter tolerance.

6 TOOTHED PULLEYS

6.4 TOOTHED PULLEY RANGE



optibelt ZRS DC toothed pulleys profile 8MDC for optibelt TB taper bushes



Type 2F Type 2 Type 3F Type 6F Type 6 Type 7 Type 8 Type 9 Type 10

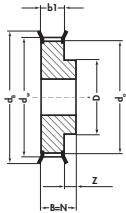
Designation	Num- ber of teeth	De- sign	Matе- rial	d _w [mm]	d _a [mm]	D _B [mm]	b ₁ [mm]	B [mm]	N [mm]	D [mm]	D _i [mm]	N [mm]	Taper bush	Weight of bush approx. [kg]
8MDC - for belt width 12														
8MDC 12 TB 25	25	2F	ST	63.66	62.06	70.0	20.0	22.0	22.0	49	—	—	1108	0.30
8MDC 12 TB 28	28	2F	ST	71.30	69.70	75.0	20.0	22.0	22.0	59	—	—	1108	0.40
8MDC 12 TB 30	30	2F	ST	76.39	74.79	82.5	20.0	25.0	25.0	60	—	—	1210	0.40
8MDC 12 TB 32	32	2F	ST	81.49	79.89	86.0	20.0	25.0	25.0	66	—	—	1610	0.40
8MDC 12 TB 34	34	2F	ST	86.58	84.98	91.0	20.0	25.0	25.0	69	—	—	1610	0.50
8MDC 12 TB 36	36	2F	ST	91.67	90.07	97.0	20.0	25.0	25.0	76	—	—	1610	0.60
8MDC 12 TB 38	38	2F	ST	96.77	95.17	102.0	20.0	25.0	25.0	78	—	—	1610	0.70
8MDC 12 TB 40	40	2F	ST	101.86	100.26	106.0	20.0	25.0	25.0	85	—	—	1610	0.90
8MDC 12 TB 45	45	2F	ST	114.59	112.99	120.0	20.0	32.0	32.0	92	—	—	2012	1.10
8MDC 12 TB 48	48	2F	ST	122.23	120.63	128.0	20.0	32.0	32.0	103	—	—	2012	1.50
8MDC 12 TB 50	50	2F	ST	127.32	125.72	135.0	20.0	32.0	32.0	104	—	—	2012	1.60
8MDC 12 TB 56	56	2F	ST	142.60	141.00	150.0	20.0	32.0	32.0	104	—	—	2012	2.10
8MDC 12 TB 60	60	2F	ST	152.79	151.19	158.0	20.0	32.0	32.0	111	—	—	2012	2.40
8MDC 12 TB 64	64	2F	ST	162.97	161.37	168.0	20.0	32.0	32.0	111	—	—	2012	2.70
8MDC 12 TB 75	75	2	GG	190.99	189.39	—	20.0	32.0	32.0	111	—	—	2012	4.60
8MDC 12 TB 80	80	2	GG	203.72	202.12	—	20.0	32.0	32.0	111	—	—	2012	5.10
8MDC 12 TB 90	90	2	GG	229.18	227.58	—	20.0	—	—	111	—	—	2012	6.40
8MDC - for belt width 21														
8MDC 21 TB 25	25	3F	ST	63.66	62.06	70.0	30.0	30.0	22.0	—	—	8.0	1108	0.40
8MDC 21 TB 28	28	3F	ST	71.30	69.70	75.0	30.0	30.0	25.0	—	—	5.0	1210	0.40
8MDC 21 TB 30	30	3F	ST	76.39	74.79	82.5	30.0	30.0	25.0	—	—	5.0	1210	0.60
8MDC 21 TB 32	32	3F	ST	81.49	79.89	86.0	30.0	30.0	25.0	—	—	5.0	1610	0.50
8MDC 21 TB 34	34	3F	ST	86.58	84.98	91.0	30.0	30.0	25.0	—	—	5.0	1610	0.60
8MDC 21 TB 36	36	3F	ST	91.67	90.07	97.0	30.0	30.0	25.0	—	—	5.0	1610	0.70
8MDC 21 TB 38	38	3F	ST	96.77	95.17	102.0	30.0	30.0	25.0	—	—	5.0	1610	1.00
8MDC 21 TB 40	40	3F	ST	101.86	100.26	106.0	30.0	30.0	25.0	—	—	5.0	1610	1.10
8MDC 21 TB 45	45	2F	ST	114.59	112.99	120.0	30.0	32.0	32.0	92	—	—	2012	1.30
8MDC 21 TB 48	48	2F	ST	122.23	120.63	128.0	30.0	32.0	32.0	103	—	—	2012	1.60
8MDC 21 TB 50	50	2F	ST	127.32	125.72	135.0	30.0	32.0	32.0	104	—	—	2012	1.90
8MDC 21 TB 56	56	2F	ST	142.60	141.00	150.0	30.0	32.0	32.0	111	—	—	2012	2.40
8MDC 21 TB 60	60	2F	ST	152.79	151.19	158.0	30.0	45.0	45.0	124	—	—	2517	3.20
8MDC 21 TB 64	64	2F	ST	162.97	161.37	168.0	30.0	45.0	45.0	124	—	—	2517	3.80
8MDC 21 TB 75	75	2	GG	190.99	189.39	—	30.0	45.0	45.0	124	—	—	2517	6.80
8MDC 21 TB 80	80	2	GG	203.72	202.12	—	30.0	45.0	45.0	124	—	—	2517	7.60

6 TOOTHED PULLEYS

6.4 TOOTHED PULLEY RANGE



optibelt ZRS DC toothed pulleys profile 8MDC for cylindrical bore



Type 1F

Designation	Number of teeth	De-sign	Material	d_w [mm]	d_a [mm]	D_8 [mm]	b_1 [mm]	B [mm]	S [mm]	D [mm]	Weight approx. [kg]
8MDC - for belt width 12											
8MDC 12 22	22	1F	ST	56.02	54.42	62.0	20.0	30.0	30.0	43	0.50
8MDC - for belt width 21											
8MDC 21 22	22	1F	ST	56.02	54.42	62.0	30.0	40.0	40.0	43	0.60
8MDC - for belt width 36											
8MDC 36 25	25	1F	ST	63.66	62.06	70.0	45.0	55.0	55.0	49	1.10
8MDC - for belt width 62											
8MDC 62 30	30	1F	ST	76.39	74.79	86.0	72.0	84.0	84.0	65	2.50
8MDC 62 32	32	1F	ST	81.49	79.89	90.0	72.0	84.0	84.0	69	2.80
8MDC 62 34	34	1F	ST	86.58	84.98	95.0	72.0	84.0	84.0	74	3.00
8MDC 62 36	36	1F	ST	91.67	90.07	98.0	72.0	84.0	84.0	77	3.40
8MDC 62 38	38	1F	ST	96.77	95.17	106.0	72.0	84.0	84.0	84	3.80

ST: Steel We reserve the right to alter specifications without notice.

6 TOOTHED PULLEYS

6.4 TOOTHED PULLEY RANGE

optibelt ZRS DC toothed pulleys profile 14MDC for optibelt TB taper bushes



RANGE OF
optibelt ZRS DC TOOTHED PULLEYS
WITH PROFILE 14MDC
UNDER DEVELOPMENT

6 TOOTHED PULLEYS

6.4 TOOTHED PULLEY RANGE



optibelt ZRS DC toothed pulleys with profile 14MDC for optibelt TB taper bushes



RANGE OF
optibelt ZRS DC TOOTHED PULLEYS
WITH PROFILE 14MDC
UNDER DEVELOPMENT

6 TOOTHED PULLEYS

6.4 TOOTHED PULLEY RANGE

optibelt ZRS DC toothed pulleys with profile 14MDC for cylindrical bore



RANGE OF
optibelt ZRS DC TOOTHED PULLEYS
WITH PROFILE 14MDC
UNDER DEVELOPMENT

7. GENERAL INFORMATION

7.1 OVERVIEW OF STANDARDS



Federal Republic of Germany

- DIN 109 Sheet 1 – Drive Elements; Circumferential Speeds
- DIN 109 Sheet 2 – Drive Elements; Centre Distances for V-Belt Drives
- DIN 111 – Pulleys for Flat Transmission Belts; Dimensions, Nominal Torques
- DIN 111 Sheet 2 – Pulleys for Flat Transmission Belts; Classification for Electrical Machines
- DIN 2211 Sheet 1 – Grooved Pulleys for Narrow V-Belts; Dimensions, Materials
- DIN 2211 Sheet 2 – Grooved Pulleys for Narrow V-Belts; Inspections of Grooves
- DIN 2211 Sheet 3 – Grooved Pulleys for Narrow V-Belts; Classification for Electrical Machines
- DIN 2215 – Endless V-Belts, Classical Profiles; Minimum Datum Diameter of the Pulleys, Internal and Datum Belt Length
- DIN 2216 – Open-Ended V-Belts; Dimensions
- DIN 2217 Sheet 1 – V-Belt Pulleys for Classical Profiles; Dimensions, Materials
- DIN 2217 Sheet 2 – V-Belt Pulleys for Classical Profiles; Inspections of Grooves
- DIN 2218 – Endless V-Belts, Classic Profiles for Mechanical Engineering; Calculation of Drives, Performance Data
- DIN 7716 – Rubber Products; Requirements for Storage, Cleaning and Maintenance
- DIN 7719 Part 1 – Endless Wide V-Belts for Industrial Speed Changers; Belts and Groove Profiles for Corresponding Pulleys
- DIN 7719 Part 2 – Endless Wide V-Belts for Industrial Speed Changers; Measurement of Centre Distance Variations
- DIN 7721 Part 1 – Synchronous Belt Drives, Metric Pitch; Synchronous Belts
- DIN 7721 Part 2 – Synchronous Belt Drives, Metric Pitch; Tooth Space Profile of Synchronous Pulleys
- DIN 7722 – Endless Hexagonal Belts for Agricultural Machines and Groove Profiles of Corresponding Pulleys
- DIN 7753 Part 1 – Endless Narrow V-Belts for Mechanical Engineering; Dimensions
- DIN 7753 Part 2 – Endless Narrow V-Belts for Mechanical Engineering; Drive Calculation, Performance Data
- DIN 7753 Part 3 – Endless Narrow V-Belts for the Automotive Industry; Dimensions
- DIN 7753 Part 4 – Endless Narrow V-Belts for the Automotive Industry; Fatigue Testing
- DIN 7867 – V-Ribbed Belts and Pulleys
- DIN/ISO 5290 – Grooved Pulleys for Joined Narrow V-Belts; Groove Profiles 9J; 15J; 20J; 25J
- DIN 22100-7 – Articles from Synthetics for Use in Underground Mines, Paragraph 5.4 – V-Belts
- DIN EN 60695-11-10
 - Fire Hazard Testing

ISO – International Organization for Standardization

- ISO 22 – Widths of Flat Transmission Belts and Corresponding Pulleys
- ISO 63 – Flat Belt Drives; Lengths
- ISO 99 – Diameter of the Belt Pulleys for Flat Belts
- ISO 100 – Bulging Height of the Belt Pulleys for Flat Belts
- ISO 155 – Belt Pulleys; Limiting Values for Adjustment of Centre Distances
- ISO 254 – Quality, Finish and Balance of Belt Pulleys
- ISO 255 – Pulleys for Classical V-Belts and Narrow V-Belts; Geometric Testing of Grooves
- ISO 1081 – Vocabulary from V-Belts, V-Ribbed Belts and Pulleys
- ISO 1604 – Endless Speed Changer Belts and Pulleys for Mechanical Engineering
- ISO 1813 – Electrical Conductivity of V-Belts, Kraftbands, V-Ribbed Belts, Wide V-Belts and Double Profile V-Belts
- ISO 2230 – Please Consult DIN 7716

- ISO 2790 – Narrow V-Belt Drives for the Automotive Industry; Dimensions
- ISO 3410 – Endless Speed Changer Belts and Pulleys for Agricultural Machinery
- ISO 4183 – Grooved Pulleys for Classical V-Belts and Narrow V-Belts
- ISO 4184 – Classical V-Belts and Narrow V-Belts; Lengths
- ISO 5256 – Synchronous Belt Drives; Belt Tooth Pitch Code Part 1 MXL; XL; L; H; XH; XXH
- ISO 5287 – Synchronous Belt Drives; Belt Tooth Pitch Code Part 2 MXL; XXL Metric Dimensions
- ISO 5287 – Narrow V-Belt Drives for the Automotive Industry; Fatigue Test
- ISO 5288 – Vocabulary from Timing Belt Drives
- ISO 5289 – Endless Double Profile V-Belts and Pulleys for Agricultural Machinery
- ISO 5290 – Grooved Pulleys for Joined Narrow V-Belts; Profiles: 9J; 15J; 20J; 25J
- ISO 5291 – Grooved Pulleys for Joined Classical V-Belts; Profiles: AJ; BJ; CJ; DJ
- ISO 5292 – Industrial V-Belt Drives; Calculations of the Performance Data and Centre Distance
- ISO 5295 – Timing Belts; Calculations of the Performance Data and Centre Distance – "Inch Pitch"
- ISO 8370-1 – Dynamic Test to Determine Pitch Zone Location with V-Belts
- ISO 8370-2 – Dynamic Test to Determine Pitch Zone Location with V-Ribbed Belts
- ISO/DIS 8419 – Belt Drives; Joined Narrow V-Belts; Lengths in Effective System; 9N/J, 15N/J, 25N/J
- ISO 9010 – Synchronous Belt Drives – Automotive Belts
- ISO 9011 – Synchronous Belt Drives – Automotive Pulleys
- ISO 9563 – Antistatic Endless Synchronous Belts; Electrical Conductibility; Characteristics and Testing Method
- ISO 9980 – Belt Drives; V-Belt Pulleys, Geometric Inspection of Grooves
- ISO 9981 – Belt Drives – Pulleys and V-Ribbed Belts for the Automotive Industry; PK Profile
- ISO 9982 – Belt Drives; Pulleys and V-Ribbed Belts for Industrial Requirements; Geometric Data PH, PJ, PK, PL, PM
- ISO 11749 – Belt Drives – V-Ribbed Belts for the Automotive Industry, Fatigue Testing
- ISO 12046 – Synchronous Belt Drives – Automotive Belts – Physical Characteristics
- ISO 13050 – Synchronous Belt Drives – Metric Pitch, Curvilinear Profile Systems G, H, R and S, Belts and Pulleys
- ISO 17396 – Synchronous Belt Drives – Metric Pitch, Trapezoidal Profile Systems T and AT, Belts and Pulleys
- ISO 19347 – Synchronous belt drives -- Imperial pitch trapezoidal profile system -- Belts and pulleys

USA

- RMA/ARPM IP-20 – Classical V-Belts and Sheaves (A; B; C; D; Cross Profiles)
- RMA/ARPM IP-21 – Double (Hexagonal) Belts (AA; BB; CC; DD Cross Profiles)
- RMA/ARPM IP-22 – Narrow Multiple V-Belts (3V; 5V; and 8V Cross Profiles)
- RMA/ARPM IP-23 – Single V-Belts (2L; 3L; 4L; and 5L Cross Profiles)
- RMA/ARPM IP-24 – Synchronous Belts (MXL; XL; L; H; XH; and XXH Belt Profiles)
- RMA/ARPM IP-25 – Variable Speed V-Belts (12 Cross Profiles)
- RMA/ARPM IP-26 – V-Ribbed Belts (PH; PJ; PK; PL; and PM Cross Profiles)
- RMA/ARPM IP-27 – Curvilinear Toothing Synchronous Belts (8M – 14M Pitches)
- ASAE S 211.... – V-Belt Drives for Agricultural Machines
- SAE J636b – V-Belts and Pulleys
- SAE J637 – Automotive V-Belt Drives

7. GENERAL INFORMATION

7.2 DATA SHEET FOR CALCULATION / CHECKING OF TIMING BELT DRIVES



For test
 For pilot production
 For series production

New drive
 Existing drive
 Requirement _____ Pieces/year

Company: _____

Street address/P.O. Box number: _____

Town or city/Post code: _____

Contact person: _____

Department: _____ Date: _____

Phone: _____ Fax: _____

E-mail: _____

Currently fitted with:

pitch length	profile	width	manufacturer

PRIME MOVER

Type (e.g. electric motor, diesel engine 3 cylinders) _____

Size of the starting torque (e.g. MA = 1.8 MN) _____

Type of start (e.g. star delta) _____

Daily operating time _____ hours

Number of starts _____ per hour per day

Change in the direction of rotation per minute per hour

Power: P normal _____ kW

P maximum _____ kW

or max. torque _____ Nm at n₁ _____ min⁻¹

Speed of driver pulley n₁ _____ min⁻¹

Shaft layout: horizontal vertical
inclined \neq _____ °

Maximum allowed static shaft loading S_a max _____ N

Pitch diameter or number of teeth on the pulley:

d_{w1} _____ mm z₁ _____ mm

d_{w1} min _____ mm z₁ min _____ mm

d_{w1} max _____ mm z₁ max _____ mm

Maximum pulley face width _____ mm

Speed ratio i _____

Drive centre distance a _____ mm

Tension/guide idler pulley: inside idler

outside idler

d_w _____ mm pulley

d_a _____ mm flat pulley

Operating conditions Ambient temperature _____

Influence of oil

water

acid

dust

DRIVEN MACHINE

Type (e.g. lathe, compressor) _____

Start: under load no load

Type of load: steady shock pulsating

Required power: P normal _____ kW

P maximal _____ kW

or max. torque _____ Nm at n₂ _____ min⁻¹

Driven speed n₂ _____ min⁻¹

n₂ min _____ min⁻¹

n₂ max _____ min⁻¹

Maximum allowed shaft loading S_a max _____ N

Pitch diameter or number of teeth on the pulley:

d_{w2} _____ mm z₂ _____ mm

d_{w2} min _____ mm z₂ min _____ mm

d_{w2} max _____ mm z₂ max _____ mm

Maximum pulley face width _____ mm

i_{min} _____ i_{max} _____

a_{min} _____ mm a_{max} _____ mm

in drive slack side

in drive tight side

moveable (e.g. spring loaded) _____

fixed

_____ °C/F minimum

_____ °C/F max.

(e.g. oil mist, drops) _____

(e.g. spray water) _____

(type, concentration, temperature) _____

(type) _____

Special drives: e.g. for drives with inside or outside tensioning/idler pulleys, three or more multi-pulley drives or for drives with contra-rotating pulleys drawings are necessary.
Please use the other side of this page for these drawings.



NOTES



NOTES

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